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# Semilinear SPDEs as Dynamical Systems (Mittag-Leffler Institute Seminar)

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# SEMILINEAR SPDEs AS DYNAMICAL SYSTEMS

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Royal Swedish Academy of Sciences

Sweden: September 25, 2007

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<sup>a</sup> Department of Mathematics, SIU-C, Carbondale, Illinois, USA

# Acknowledgment

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- Research supported by (US) NSF Grants DMS-9703852, DMS-9975462, DMS-0203368 and DMS-0705970.

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- Stable manifolds. ([M.Z.Z]).

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$$\theta(t, \omega)(s) := \omega(t + s) - \omega(t), \quad t, s \in \mathbf{R}, \omega \in \Omega.$$

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- $d\xi :=$  Riemannian volume on  $M$ .

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- $L^{(j)}(H) :=$  continuous  $H$ -valued  $j$ -multilinear maps on  $H$ .

# Examples: Affine Linear SEEs

*Affine Linear SEEs (Additive Noise):*

$$\left. \begin{aligned} du(t, x) &= -Au(t, x) dt + B_0 dW(t), \quad t > 0 \\ u(0, x) &= x \in H. \end{aligned} \right\}$$

$A$  hyperbolic:  $0 \notin \sigma(A)$ —discrete bounded below.

$W$  Brownian motion with covariance Hilbert space  $K$ .

$B_0 : K \rightarrow H$ , Hilbert Schmidt. **Mild solutions.**

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$W$  Brownian motion with covariance Hilbert space  $K$ .

$B_0 : K \rightarrow H$ , Hilbert Schmidt. **Mild solutions.**

See has stationary solution, and affine linear semiflow on  $H$ .

# Reaction-Diffusion Equations

*Stochastic Reaction-Diffusion Equation:*

$$du = \frac{1}{2} \Delta u dt + (1 - |u|^\alpha) u dt + \sum_{i=1}^{\infty} \sigma_i u dW_i(t),$$

$W_i$  := independent standard Brownian motions on  $\mathbf{R}$ .

$\sigma_i \in H_0^s(M, \mathbf{R})$ ,  $s > 2 + d/2$ ;  $\sum_{i=1}^{\infty} \|\sigma_i\|_{H_0^s}^2 < \infty$ .

Dirichlet boundary conditions. **Weak solutions.**

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Dirichlet boundary conditions. **Weak solutions.**

Has  $C^1$  stochastic semiflow on  $H := L^2(M, \mathbf{R})$  for

$$\alpha < \frac{4}{d}.$$

Lipschitz semiflow for  $\alpha$  even integer.



# Stochastic Heat Equation

*Stochastic Heat Equation:*

$$du(t) = \frac{1}{2} \Delta u(t) dt + \sum_{i=1}^{\infty} \sigma_i u(t) dW_i(t) + f(u(t)) dt$$

$$u(0) = \psi \in H_0^k(M)$$

$W_i$  as above;  $\sigma_i \in H_0^s(M, \mathbf{R})$ ,  $\sum_{i=1}^{\infty} \|\sigma_i\|_{H_0^s}^2 < \infty$ ,  
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Dirichlet boundary conditions. **Weak solutions.**

Has  $C^\infty$  stochastic semiflow on  $H_0^k(M)$  for  $k > \frac{d}{2}$ .

# Semilinear Parabolic SPDEs

## *Semilinear Parabolic SPDEs:*

In stochastic heat equation replace  $\Delta$  by a second order self-adjoint elliptic linear differential operator:

$$L := \sum_{i,j=1}^d a_{ij}(\xi) \frac{\partial^2}{\partial \xi_i \partial \xi_j} + \sum_{i=1}^d b_i(\xi) \frac{\partial}{\partial \xi_i}$$

on  $M$ .

Dirichlet boundary condition. **Weak solutions.**

Smooth coefficients  $a_{i,j} : M \rightarrow \mathbf{R}$ ,  $b_i : M \rightarrow \mathbf{R}$ .

# Parabolic SPDEs-contd

View parabolic spde as a **semilinear stochastic evolution equation** (see):

$$du(t) = -Au(t) dt + F(u(t)) dt + \sum_{i=1}^{\infty} B_i u(t) dW_i(t)$$

$$u(0) = x \in H := H_0^k(M).$$

$$A := -L, \quad B_i(u) := \sigma_i u, \quad F(u) := f \circ u, \quad u \in H.$$

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$$A := -L, \quad B_i(u) := \sigma_i u, \quad F(u) := f \circ u, \quad u \in H.$$

Let  $k > \frac{d}{2}$ . Then **Nemytskii operator**  $F : H \rightarrow H$  is  $C^\infty$ .

Smooth stochastic semiflow on  $H_0^k(M)$ .

# Burgers Equation

Considered by many authors in recent years. (e.g. [E.K.M.S]).

One-dimensional *stochastic Burgers equation*:

$$du + u \frac{\partial u}{\partial \xi} dt = \frac{1}{2} \frac{\partial^2 u}{\partial \xi^2} dt + \sum_{i=1}^{\infty} \sigma_i(\xi) dW_i(t)$$

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$W_i$  independent one dimensional Brownian motions.

$\sigma_i \in C^2([0, 1])$ ;  $\|\sigma_i\|_{C^2} \leq \frac{C}{i^2}$ ,  $i \geq 1$ . **Mild solutions.**

Has  $C^1$  stochastic semiflow on  $L^2([0, 1], \mathbf{R})$ .

# The Cocycle

---

$k =$  non-negative integer,  $\epsilon \in (0, 1]$ .  $H$  Hilbert.

A  $C^{k,\epsilon}$  **perfect cocycle**  $(U, \theta)$  on  $H$  is a measurable random field  $U : \mathbf{R}^+ \times H \times \Omega \rightarrow H$  such that:



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- For each  $\omega \in \Omega$ , the map

$$\mathbf{R}^+ \times H \ni (t, x) \mapsto U(t, x, \omega) \in H$$

is continuous; for fixed  $(t, \omega) \in \mathbf{R}^+ \times \Omega$ , the map

$$H \ni x \mapsto U(t, x, \omega) \in H$$

is  $C^{k,\epsilon}$  ( $D^k U(t, x, \omega)$  is  $C^\epsilon$  in  $x$  on bounded sets in  $H$ ).

# The Cocycle-Contd

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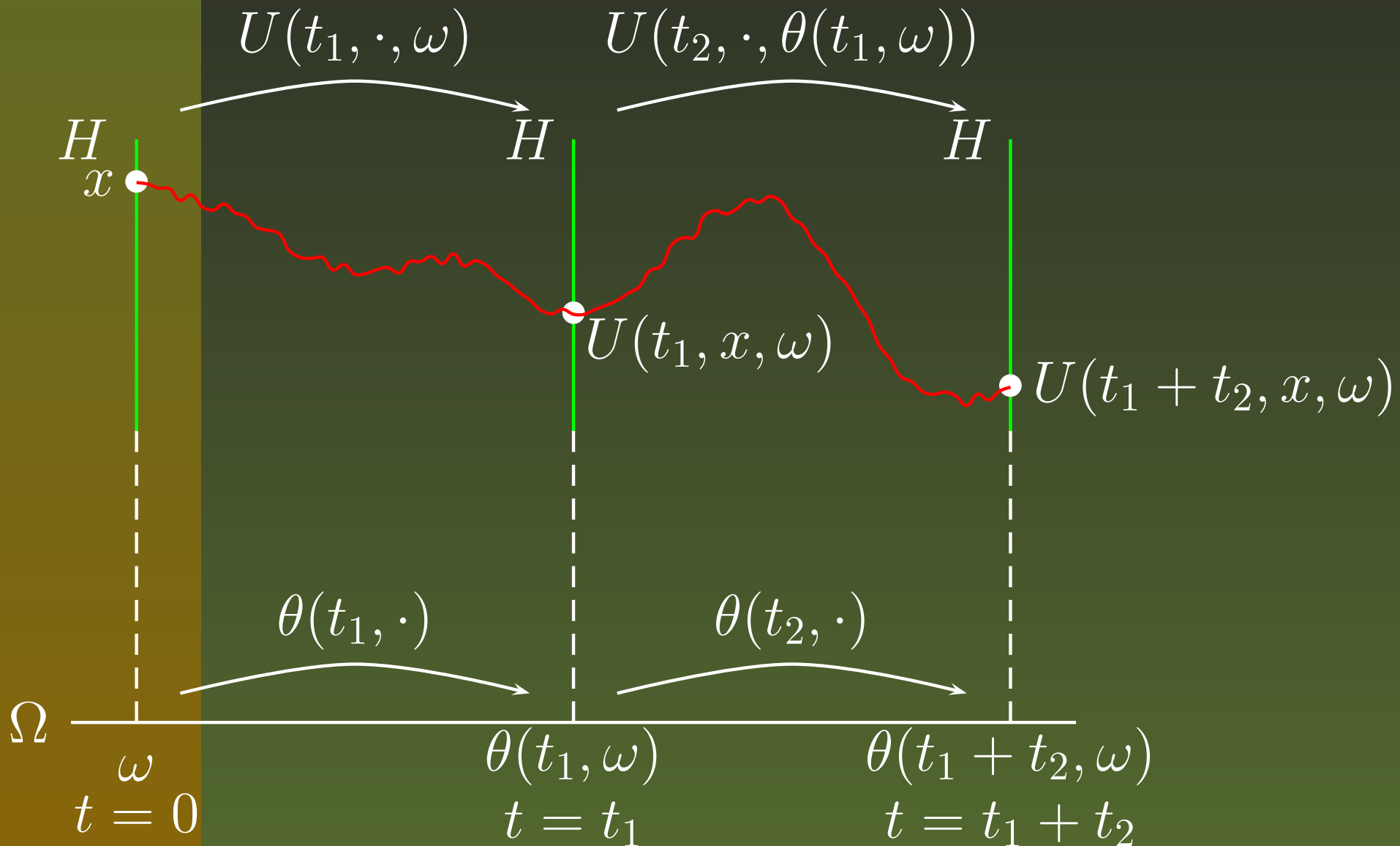
- $U(t_1 + t_2, \cdot, \omega) = U(t_2, \cdot, \theta(t_1, \omega)) \circ U(t_1, \cdot, \omega)$   
for all  $t_1, t_2 \in \mathbf{R}^+$ , all  $\omega \in \Omega$ .

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for all  $t_1, t_2 \in \mathbf{R}^+$ , all  $\omega \in \Omega$ .
- $U(0, x, \omega) = x$  for all  $x \in H, \omega \in \Omega$ .

# The Cocycle Property



# Stationary Point

---

A random variable  $Y : \Omega \rightarrow H$  is a *stationary point* for the cocycle  $(U, \theta)$  if

$$U(t, Y(\omega), \omega) = Y(\theta(t, \omega))$$

for all  $t \in \mathbb{R}^+$  and every  $\omega \in \Omega$ .

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Denote a stationary trajectory by

$$U(t, Y) = Y(\theta(t)).$$

For sde's: a non-anticipating stationary point corresponds to an invariant measure for the one-point motion.

# Linearization

---

Linearize a  $C^{k,\epsilon}$  cocycle  $(U, \theta)$  along a stationary random point  $Y$ :

Get an  $L(H)$ -valued cocycle  $(DU(t, Y(\omega), \omega), \theta(t, \omega))$ .



# Linearization

Linearize a  $C^{k,\epsilon}$  cocycle  $(U, \theta)$  along a stationary random point  $Y$ :

Get an  $L(H)$ -valued cocycle  $(DU(t, Y(\omega), \omega), \theta(t, \omega))$ .

Follows from cocycle property of  $U$  and chain rule:

$$\begin{aligned} & DU(t_1 + t_2, Y(\omega), \omega) \\ &= DU(t_2, Y(\theta(t_1, \omega)), \theta(t_1, \omega)) \circ DU(t_1, Y(\omega), \omega) \end{aligned}$$

for all  $\omega \in \Omega, t_1, t_2 \geq 0$ .

# Linearization-contd

---

Assume  $U(t, \cdot, \omega)$  locally compact and

$$E \log^+ \sup_{0 \leq t_1, t_2 \leq 1} \|DU(t_2, Y(\theta(t_1)), \theta(t_1))\|_{L(H)} < \infty.$$

Apply **Oseledec-Ruelle Theorem** to linearized cocycle  
([Ru.2]):

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Apply **Oseledec-Ruelle Theorem** to linearized cocycle

(**[Ru.2]**):

Get a sequence of closed finite-codimensional **Oseledec spaces**

$$\cdots E_{i+1}(\omega) \subset E_i(\omega) \subset \cdots \subset E_2(\omega) \subset E_1(\omega) = H,$$

all  $\omega \in \Omega^*$ , a sure event in  $\mathcal{F}$  satisfying  $\theta(t, \cdot)(\Omega^*) = \Omega^*$   
for all  $t \in \mathbb{R}$ .

# Linearization-contd

Obtain Lyapunov spectrum

$$\{\cdots < \lambda_{i+1} < \lambda_i < \cdots < \lambda_2 < \lambda_1\};$$

$$\lim_{t \rightarrow \infty} \frac{1}{t} \log |DU(t, Y(\omega), \omega)(x)|$$

$$= \begin{cases} \lambda_i & \text{if } x \in E_i(\omega) \setminus E_{i+1}(\omega), \\ -\infty & \text{if } x \in E_\infty(\omega). \end{cases}$$

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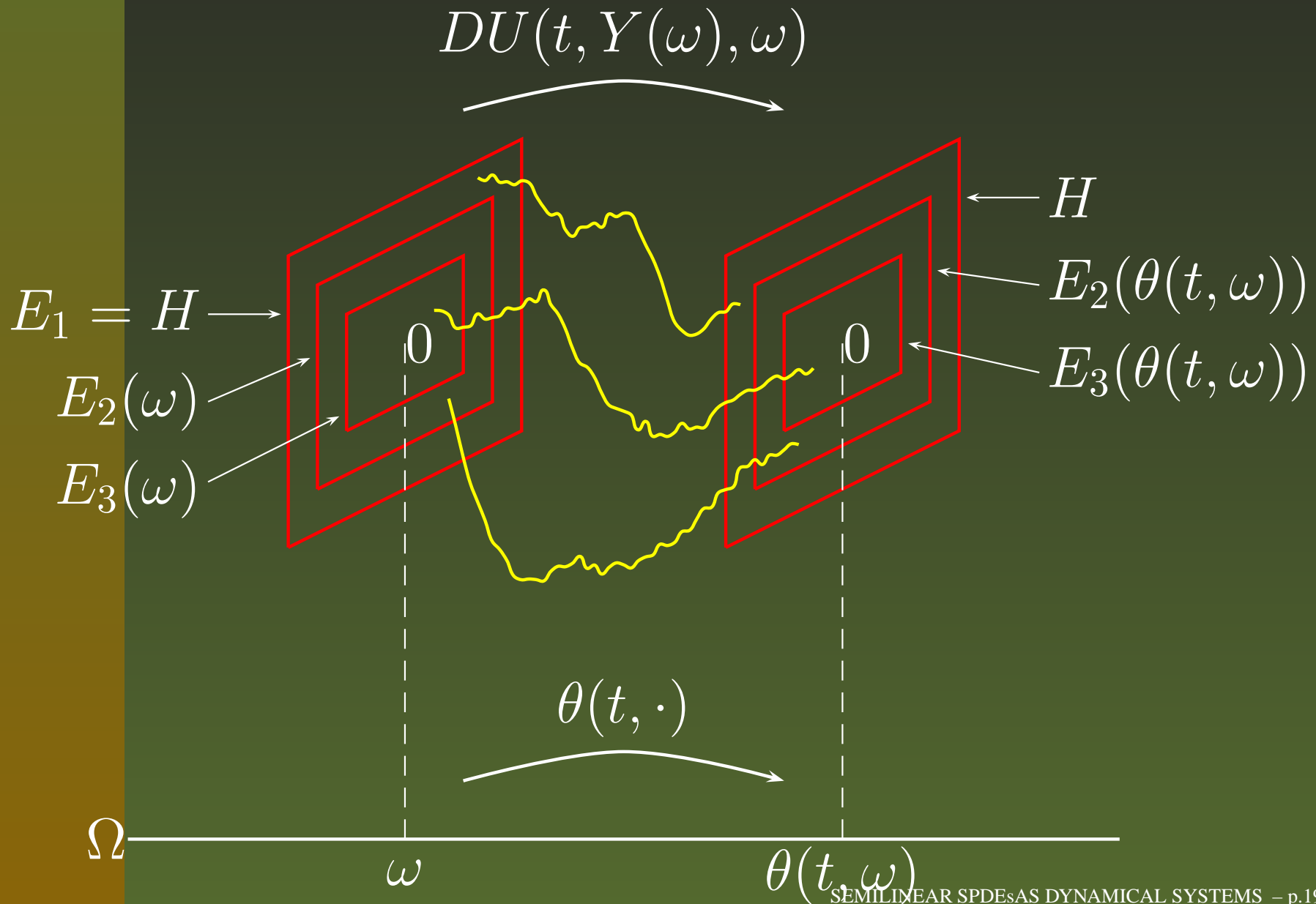
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$$E_i(\omega) = \{x \in H : \lim_{t \rightarrow \infty} \frac{1}{t} \log |DU(t, Y(\omega), \omega)(x)| \leq \lambda_i\},$$

$$i \geq 1.$$

# Linearization: Spectral Theorem



# Hyperbolicity

A stationary point  $Y(\omega)$  of  $(U, \theta)$  is *hyperbolic* if the linearized cocycle  $(DU(t, Y(\omega), \omega), \theta(t, \omega))$  has a *non-zero* Lyapunov spectrum

$$\{\dots < \lambda_{i+1} < \lambda_i < \dots < \lambda_2 < \lambda_1\}.$$

That is

$$\lambda_i \neq 0 \quad \text{for all } i \geq 1.$$

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(Expect *hyperbolicity* to be a “*generic*” property.)

*Ergodicity*:  $\lambda_1 < 0$ .

# Hyperbolicity-Contd

---

$\{\mathcal{U}(\omega), \mathcal{S}(\omega) : \omega \in \Omega^*\}$  := unstable and stable subspaces associated with the linearized cocycle  $(DU, \theta)$  ([Mo.3], [M.S]).

# Hyperbolicity-Contd

$\{\mathcal{U}(\omega), \mathcal{S}(\omega) : \omega \in \Omega^*\}$  := unstable and stable subspaces associated with the linearized cocycle  $(DU, \theta)$  ([Mo.3], [M.S]).

Then get a measurable invariant splitting

$$H = \mathcal{U}(\omega) \oplus \mathcal{S}(\omega), \quad \omega \in \Omega^*,$$

$$DU(t, Y(\omega), \omega)(\mathcal{U}(\omega)) = \mathcal{U}(\theta(t, \omega)),$$

$$DU(t, Y(\omega), \omega)(\mathcal{S}(\omega)) \subseteq \mathcal{S}(\theta(t, \omega)),$$

for all  $t \geq 0$ .

# Hyperbolicity-Contd

Have **exponential dichotomies**:

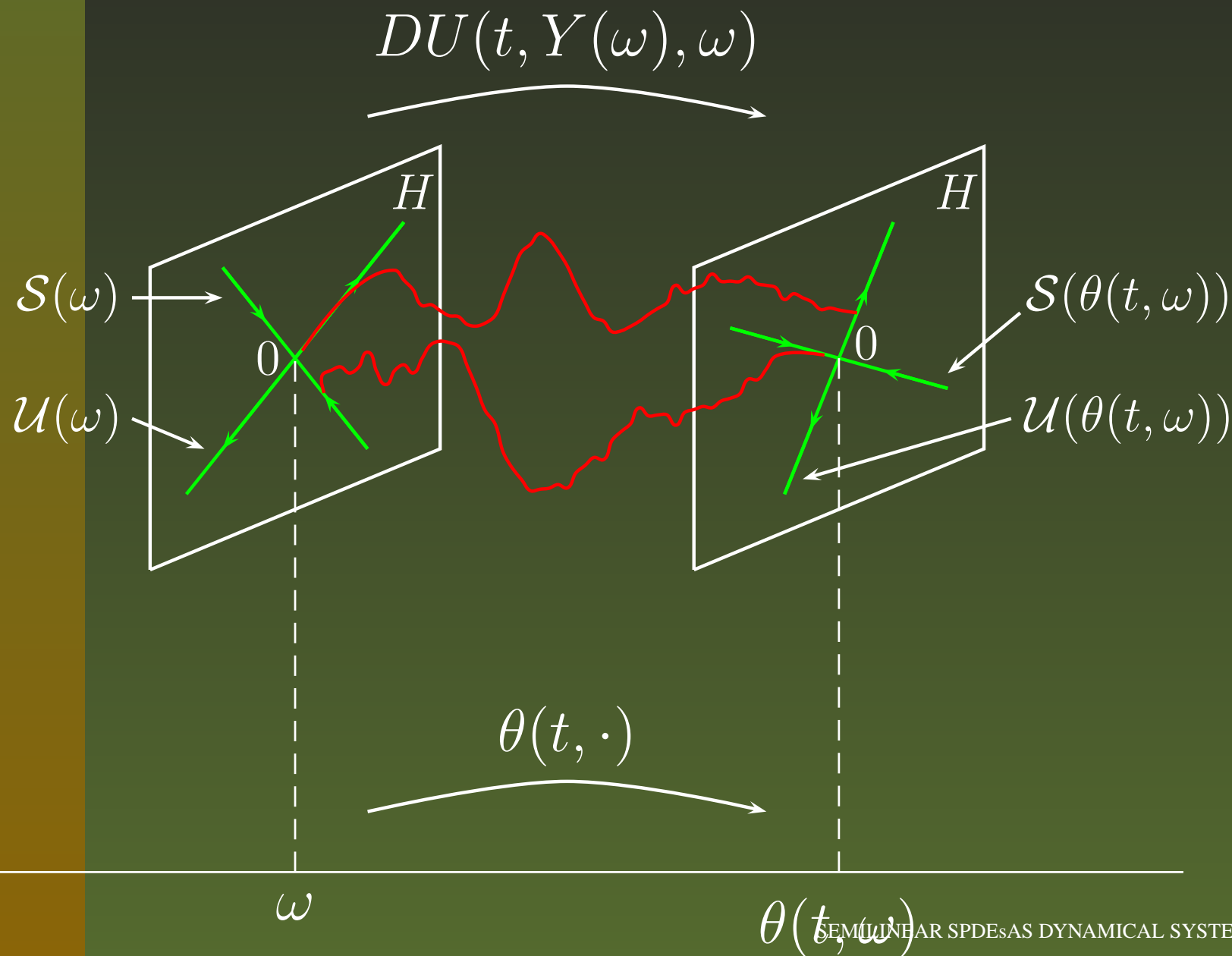
$$|DU(t, Y(\omega), \omega)(x)| \geq |x|e^{\delta_1 t}$$

for all  $t \geq \tau_1^*$ ,  $x \in \mathcal{U}(\omega)$ ;

$$|DU(t, Y(\omega), \omega)(x)| \leq |x|e^{-\delta_2 t}$$

for all  $t \geq \tau_2^*$ ,  $x \in \mathcal{S}(\omega)$ , with  $\tau_i^* = \tau_i^*(x, \omega) > 0$ , **random** times and  $\delta_i > 0$ , **fixed**,  $i = 1, 2$ .

# Hyperbolicity-Contd



# Linear SDEs

---

Existence of semiflows for mild solutions of linear SDEs:

$$du(t, x, \cdot) = -Au(t, x, \cdot) dt + Bu(t, x, \cdot) dW(t),$$
$$t > 0$$

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$A : D(A) \subset H \rightarrow H$  closed linear operator on a separable real Hilbert space  $H$ .

$A$  has complete orthonormal system of eigenvectors  $\{e_n : n \geq 1\}$  with corresponding (bounded below) (non-zero) eigenvalues  $\{\mu_n, n \geq 1\}$ ; i.e.,

$$Ae_n = \mu_n e_n, \quad n \geq 1;$$

e.g.  $A = -\Delta$  on compact smooth Riemannian manifold.

# Linear SEEs-Contd

---

$(-A)$  generates a strongly continuous semigroup of bounded linear operators

$$T_t : H \rightarrow H, t \geq 0.$$

$W(t), t \geq 0$ ,  $E$ -valued cylindrical Brownian motion on canonical filtered Wiener space  $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)$ .  
 $K \subset E$  Hilbert-Schmidt embedding. ([D.Z]).



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 $K \subset E$  Hilbert-Schmidt embedding. ([D.Z]).

$L_2(K, H) :=$  **Hilbert space** of all Hilbert-Schmidt operators  $S : K \rightarrow H$ ; H-S norm

$$\|S\|_2 := \left[ \sum_{k=1}^{\infty} |S(f_k)|^2 \right]^{1/2},$$

# Linear SEEs-Contd

---

$f_k, k \geq 1$ , cons in  $K$ .

$|\cdot| :=$  norm on  $H$ .  $L_2(H) := L_2(H, H)$ .

$B : H \rightarrow L_2(K, H)$  bounded (affine) linear operator.

Stochastic integral in (see) as in ([D.Z] ).

# Linear SEEs-Contd

$f_k, k \geq 1$ , cons in  $K$ .

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$B : H \rightarrow L_2(K, H)$  bounded (affine) linear operator.

Stochastic integral in (see) as in ([D.Z] ).

$\theta : \mathbf{R} \times \Omega \rightarrow \Omega$  standard  $P$ -preserving ergodic Wiener shift on  $\Omega$ .  $(W, \theta)$  is a *helix*:

$$W(t_1 + t_2, \omega) - W(t_1, \omega) = W(t_2, \theta(t_1, \omega))$$

for all  $t_1, t_2 \in \mathbf{R}, \omega \in \Omega$ .

# Mild Solutions

A *mild solution* of the linear see is a family of  $(\mathcal{B}(\mathbf{R}^+) \otimes \mathcal{F}, \mathcal{B}(H))$ -measurable,  $(\mathcal{F}_t)_{t \geq 0}$ -adapted processes  $u(\cdot, x, \cdot) : \mathbf{R}^+ \times \Omega \rightarrow H$ ,  $x \in H$ , s.t.

$$u(t, x, \cdot) = T_t x + \int_0^t T_{t-s} B u(s, x, \cdot) dW(s), \quad t \geq 0.$$

Integral equation holds  *$x$ -almost surely*,  $x \in H$ .

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Integral equation holds  *$x$ -almost surely*,  $x \in H$ .

Is  $u(t, x, \cdot)$  pathwise continuous linear in  $x$ ?

# Kolmogorov Fails!

---

*Kolmogorov's continuity theorem fails* for random field

$$I : L^2([0, 1], \mathbf{R}) \rightarrow L^2(\Omega, \mathbf{R})$$

$$I(x) := \int_0^1 x(t) dW(t), \quad x \in L^2([0, 1], \mathbf{R}).$$

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No **continuous** (or even **Borel measurable linear!**)  
selection

$$L^2([0, 1], \mathbf{R}) \times \Omega \rightarrow \mathbf{R}$$

$$(x, \omega) \mapsto I(x, \omega)$$

of  $I$  ([Mo.1]).

# Lifting

---

- Lift semigroup  $T_t, t \geq 0$ , to a strongly continuous semigroup of bounded linear operators

$\tilde{T}_t : L_2(K, H) \rightarrow L_2(K, H), t \geq 0$ , via composition

$\tilde{T}_t(C) := T_t \circ C, C \in L_2(K, H), t \geq 0.$



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 $\tilde{T}_t(C) := T_t \circ C, C \in L_2(K, H), t \geq 0$ .

- Lift stochastic integral

$$\int_0^t \tilde{T}_{t-s}(\{[B \circ v(s)](x)\}) dW(s), \quad x \in H, t \geq 0,$$

to  $L_2(H)$  for adapted square-integrable  
 $v : \mathbf{R}^+ \times \Omega \rightarrow L_2(H)$ . Denote lifting by

$$\int_0^t T_{t-s} B v(s) dW(s).$$

# Lifting-contd

That is:

$$\left[ \int_0^t T_{t-s} B v(s) dW(s) \right] (x) = \int_0^t \tilde{T}_{t-s}(\{[B \circ v(s)](x)\}) dW(s)$$

for all  $t \geq 0$ ,  $x$ -a.s..

# Regularity Hypotheses

---

- *Hypothesis (A1):*

$$\sum_{n=1}^{\infty} \mu_n^{-1} \|B(e_n)\|_{L_2(K,H)}^2 < \infty.$$

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For some  $\alpha \in (0, 1)$ ,  $A^{-\alpha}$  is trace-class, i.e.,

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---

- *Hypothesis (A3):*

$A^{-1}$  is trace-class and  $T_t \in L(H)$ ,  $t \geq 0$ , is a strongly continuous contraction semigroup.

# Regularity Hypotheses-contd

---

- *Hypothesis (B)*:

$B : H \rightarrow L_2(K, H)$  extends to a bounded linear operator  $B \in L(H, L(E, H))$  ;  $\sum_{k=1}^{\infty} \|B_k\|^2 < \infty$ ,

where  $B_k \in L(H)$  is defined by

$$B_k(x) := B(x)(f_k), x \in H, k \geq 1.$$

---

No restriction on  $\dim M$  under (A1) for examples of spdes: e.g.  $B \in L_2(H, L_2(K, H))$ .

# Theorem 1: The Linear Flow

---

*Assume hypothesis (B) and any one of hypotheses (A1), (A2) or (A3). Then the mild solution of the linear see has a Borel (strongly) measurable  $(\mathcal{F}_t)_{t \geq 0}$ -adapted version  $\phi : \mathbf{R}^+ \times \Omega \rightarrow L(H)$  with the following properties:*

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- Under (A2),

$$E \sup_{0 \leq t \leq a} \|\phi(t, \cdot)\|_{L(H)}^{2p} < \infty,$$

whenever  $p \in (1, \alpha^{-1}]$ ,  $a \in \mathbf{R}^+$ .



# Theorem 1-Contd: “Chaos”!

- For each  $t > 0$  and almost all  $\omega \in \Omega$ ,  $\phi(t, \omega) - T_t \in L_2(H)$  has “chaos-type” representation

$$\begin{aligned} \phi(t, \cdot) - T_t = & \sum_{n=1}^{\infty} \int_0^t T_{t-s_1} B \int_0^{s_1} T_{s_1-s_2} B \cdots \\ & \cdots \int_0^{s_{n-1}} T_{s_{n-1}-s_n} B T_{s_n} dW(s_n) \\ & \cdots dW(s_2) dW(s_1). \end{aligned}$$

*Iterated Itô stochastic integrals are lifted integrals in  $L_2(H)$ , and series converges absolutely in  $L_2(H)$ .*

# Theorem 1-contd

---

- *Under (A1) or (A3),*

$$E \sup_{0 \leq t \leq a} \|\phi(t, \cdot)\|_{L(H)}^2 < \infty,$$

# Theorem 1-contd

- Under (A1) or (A3),

$$E \sup_{0 \leq t \leq a} \|\phi(t, \cdot)\|_{L(H)}^2 < \infty,$$

- $(\phi, \theta)$  is a perfect  $L(H)$ -valued cocycle:

$$\phi(t + s, \omega) = \phi(t, \theta(s, \omega)) \circ \phi(s, \omega)$$

for all  $s, t \geq 0$  and all  $\omega \in \Omega$ ;

# Theorem 1-contd

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for all  $s, t \geq 0$  and all  $\omega \in \Omega$ ;

- $\sup_{0 \leq s \leq t \leq a} \|\phi(t - s, \theta(s, \omega))\|_{L(H)} < \infty$ , for all  $\omega \in \Omega$   
and all  $a > 0$ .

# Semilinear SEE

Consider the **semilinear** stochastic evolution equation:

$$\left. \begin{aligned} du(t) &= -Au(t)dt + F(u(t))dt \\ &\quad + Bu(t) dW(t), \quad t > 0, \\ u(0) &= x \in H \end{aligned} \right\}$$

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Operators  $A, B$  satisfy hypothesis (B) and any one of hypotheses (A1), (A2) or (A3) (of Theorem 1).

$F : H \rightarrow H$  is (Fréchet)  $C^{k,\epsilon}$  ( $k \geq 1$ ), with linear growth:

$$|F(v)| \leq C(1 + |v|), \quad v \in H$$

for some positive constant  $C$ .

# Mild Solution: Semilinear SDE

Define a *mild solution* of semilinear SDE as a family of  $(\mathcal{B}(\mathbf{R}^+) \otimes \mathcal{F}, \mathcal{B}(H))$ -measurable,  $(\mathcal{F}_t)_{t \geq 0}$ -adapted processes  $u(\cdot, x, \cdot) : \mathbf{R}^+ \times \Omega \rightarrow H$ ,  $x \in H$ , satisfying:

$$u(t, x, \cdot) = T_t(x) + \int_0^t T_{t-s}(F(u(s, x, \cdot))) ds + \int_0^t T_{t-s} B u(s, x, \cdot) dW(s),$$

for all  $t \geq 0$ ,  $x$ -a.s. ([D-Z]).

# Random Integral Equation

Obtain a  $C^k$  perfect cocycle  $(U, \theta)$  for mild solutions of the semilinear see, via the **random** integral equation on  $H$ :

$$U(t, x, \omega) = \phi(t, \omega)(x) + \int_0^t \phi(t-s, \theta(s, \omega))(F(U(s, x, \omega))) ds,$$

each  $\omega \in \Omega$ ,  $t \geq 0$ ,  $x \in H$ .



# Theorem 2

*Assume that the operators  $A, B$  satisfy hypothesis (B) and (A1) (or (A2) or (A3)). Let  $T_t, t > 0$ , be compact. Suppose that  $F : H \rightarrow H$  is  $C^{k,\epsilon}$  and has linear growth. Then the mild solution of the semilinear see has a Borel measurable version*

$$U : \mathbf{R}^+ \times H \times \Omega \rightarrow H$$

*with the following properties:*

- *For each  $x \in H$ ,  $U(\cdot, x, \cdot) : \mathbf{R}^+ \times \Omega \rightarrow H$  is  $(\mathcal{F}_t)_{t \geq 0}$ -adapted and is a mild solution of the semilinear see.*

# Theorem 2-contd

---

- $(U, \theta)$  is a  $C^{k, \epsilon}$  perfect cocycle.

# Theorem 2-contd

---

- $(U, \theta)$  is a  $C^{k, \epsilon}$  perfect cocycle.
- For each  $(t, \omega) \in (0, \infty) \times \Omega$ , the map

$$H \ni x \mapsto U(t, x, \omega) \in H$$

*takes bounded sets into relatively compact sets.*

# Theorem 2-contd

- For each  $(t, x, \omega) \in (0, \infty) \times H \times \Omega$ ,  $1 \leq j \leq k$ , the  $j$ -th Fréchet derivative  $D^{(j)}U(t, x, \omega) \in L^{(j)}(H)$  is compact, and the map

$$[0, \infty) \times H \times \Omega \ni$$

$$(t, x, \omega) \mapsto D^{(j)}U(t, x, \omega) \in L^{(j)}(H)$$

is strongly measurable.

$L^{(j)}(H) :=$  continuous  $H$ -valued  $j$ -multilinear maps on  $H$ .

# Theorem 2-contd

- For any positive  $a, \rho$ ,

$$E \sup_{\substack{0 \leq t \leq a \\ |x| \leq \rho \\ 1 \leq j \leq k}} \left\{ \|D^{(j)}U(t, x, \cdot)\|_{L^{(j)}(H)} \right\} < \infty,$$

and

$$E \left\{ \sup_{\substack{0 \leq t \leq a \\ x \in \bar{H}}} \frac{|U(t, x, \cdot)|^{2p}}{(1 + |x|^{2p})} \right\} < \infty$$

for all positive integers  $p$ .

# The Stable Manifold Theorem

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# The Stable Manifold Theorem

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# Theorem 3: Stable Manifolds

---

*Assume that the operators  $A, B$  satisfy hypothesis (B) and (A1) (or (A2) or (A3)). Let  $T_t, t > 0$ , be compact. Suppose that  $F : H \rightarrow H$  is  $C^{k,\epsilon}$  and has linear growth. Let  $Y : \Omega \rightarrow H$  be a hyperbolic stationary point of the semilinear see such that  $E(|Y(\cdot)|_H^{\epsilon_0}) < \infty$  for some  $\epsilon_0 > 0$ .*

# Theorem 3: Stable Manifolds

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*Denote by*

$$\{\dots < \lambda_{i+1} < \lambda_i < \dots < \lambda_2 < \lambda_1\}$$

*the Lyapunov spectrum of the linearized cocycle  $(DU(t, Y(\omega), \omega), \theta(t, \omega), t \geq 0)$  of the semilinear see.*

# Theorem 3-contd

*Let  $\lambda_{i_0} :=$  the largest negative Lyapunov exponent of the linearized cocycle, and  $\lambda_{i_0-1}$  its smallest positive Lyapunov exponent:*

$$\{\cdots < \lambda_{i+1} < \lambda_i < \cdots < \lambda_{i_0} < 0 < \lambda_{i_0-1} < \cdots < \lambda_1\}.$$

*Fix  $\epsilon_1 \in (0, -\lambda_{i_0})$  and  $\epsilon_2 \in (0, \lambda_{i_0-1})$ :*

$$\{\cdots < \lambda_i < \cdots < \lambda_{i_0} < -\epsilon_1 < 0 < \epsilon_2 < \lambda_{i_0-1} < \cdots < \lambda_1\}.$$

# Theorem 3-contd

---

*Then the following exist:*

- *a sure event  $\Omega^* \in \mathcal{F}$  with  $\theta(t, \cdot)(\Omega^*) = \Omega^*$  for all  $t \in \mathbf{R}$ ,*
- *$\bar{\mathcal{F}}$ -measurable random variables  $\rho_i, \beta_i : \Omega^* \rightarrow (0, 1)$ ,  $\beta_i > \rho_i > 0$ ,  $i = 1, 2$ , such that for each  $\omega \in \Omega^*$ , the following is true:*

# Theorem 3-contd

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- *a sure event  $\Omega^* \in \mathcal{F}$  with  $\theta(t, \cdot)(\Omega^*) = \Omega^*$  for all  $t \in \mathbf{R}$ ,*
- *$\bar{\mathcal{F}}$ -measurable random variables  $\rho_i, \beta_i : \Omega^* \rightarrow (0, 1)$ ,  $\beta_i > \rho_i > 0$ ,  $i = 1, 2$ , such that for each  $\omega \in \Omega^*$ , the following is true:*

*There are  $C^{k, \epsilon}$  ( $\epsilon \in (0, \delta)$ ) submanifolds  $\tilde{\mathcal{S}}(\omega)$ ,  $\tilde{\mathcal{U}}(\omega)$  of  $\bar{B}(Y(\omega), \rho_1(\omega))$  and  $\bar{B}(Y(\omega), \rho_2(\omega))$  (resp.) with the following properties:*

# Theorem 3-contd

(a)  $\tilde{\mathcal{S}}(\omega)$  is the set of all  $x \in \bar{B}(Y(\omega), \rho_1(\omega))$  such that

$$|U(n, x, \omega) - Y(\theta(n, \omega))| \leq \beta_1(\omega) e^{(\lambda_{i_0} + \epsilon_1)n}$$

for all integers  $n \geq 0$ . Furthermore,

$$\limsup_{t \rightarrow \infty} \frac{1}{t} \log |U(t, x, \omega) - Y(\theta(t, \omega))| \leq \lambda_{i_0}$$

for all  $x \in \tilde{\mathcal{S}}(\omega)$ .

# Theorem 3-contd

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$$|U(n, x, \omega) - Y(\theta(n, \omega))| \leq \beta_1(\omega) e^{(\lambda_{i_0} + \epsilon_1)n}$$

for all integers  $n \geq 0$ . Furthermore,

$$\limsup_{t \rightarrow \infty} \frac{1}{t} \log |U(t, x, \omega) - Y(\theta(t, \omega))| \leq \lambda_{i_0}$$

for all  $x \in \tilde{\mathcal{S}}(\omega)$ . Each stable subspace  $\mathcal{S}(\omega)$  of the linearized semiflow  $DU$  is tangent at  $Y(\omega)$  to the submanifold  $\tilde{\mathcal{S}}(\omega)$ , viz.  $T_{Y(\omega)}\tilde{\mathcal{S}}(\omega) = \mathcal{S}(\omega)$ .



# Theorem 3-contd

*In particular,  $\text{codim } \tilde{\mathcal{S}}(\omega) = \text{codim } \mathcal{S}(\omega)$ , is fixed and finite.*

$$(b) \limsup_{t \rightarrow \infty} \frac{1}{t} \log \left[ \sup \left\{ \frac{|U(t, x_1, \omega) - U(t, x_2, \omega)|}{|x_1 - x_2|} : \right. \right. \\ \left. \left. x_1 \neq x_2, x_1, x_2 \in \tilde{\mathcal{S}}(\omega) \right\} \right] \leq \lambda_{i_0}.$$

# Theorem 3-contd

---

*(c) (Cocycle-invariance of the stable manifolds):*

*There exists  $\tau_1(\omega) \geq 0$  such that*

$$U(t, \cdot, \omega)(\tilde{\mathcal{S}}(\omega)) \subseteq \tilde{\mathcal{S}}(\theta(t, \omega))$$

*for all  $t \geq \tau_1(\omega)$ . Also*

$$DU(t, Y(\omega), \omega)(\mathcal{S}(\omega)) \subseteq \mathcal{S}(\theta(t, \omega)), \quad t \geq 0.$$

# Theorem 3-contd

(d)  $\tilde{\mathcal{U}}(\omega)$  is the set of all  $x \in \bar{B}(Y(\omega), \rho_2(\omega))$  with the property that there is a unique *discrete-time history process*  $y(\cdot, \omega) : \{-n : n \geq 0\} \rightarrow H$  such that  $y(0, \omega) = x$  and for each integer  $n \geq 1$ , one has

$$U(1, y(-n, \omega), \theta(-n, \omega)) = y(-(n-1), \omega)$$

and

$$|y(-n, \omega) - Y(\theta(-n, \omega))| \leq \beta_2(\omega) e^{-(\lambda_{i_0-1} - \epsilon_2)n}.$$

# Theorem 3-contd

Furthermore, for each  $x \in \tilde{\mathcal{U}}(\omega)$ , there is a unique *continuous-time history process* also denoted by  $y(\cdot, \omega) : (-\infty, 0] \rightarrow H$  such that  $y(0, \omega) = x$ ,  $U(t, y(s, \omega), \theta(s, \omega)) = y(t + s, \omega)$  for all  $s \leq 0$ ,  $0 \leq t \leq -s$ , and

$$\limsup_{t \rightarrow \infty} \frac{1}{t} \log |y(-t, \omega) - Y(\theta(-t, \omega))| \leq -\lambda_{i_0-1}.$$

# Theorem 3-contd

Furthermore, for each  $x \in \tilde{\mathcal{U}}(\omega)$ , there is a unique *continuous-time history process* also denoted by  $y(\cdot, \omega) : (-\infty, 0] \rightarrow H$  such that  $y(0, \omega) = x$ ,  $U(t, y(s, \omega), \theta(s, \omega)) = y(t + s, \omega)$  for all  $s \leq 0$ ,  $0 \leq t \leq -s$ , and

$$\limsup_{t \rightarrow \infty} \frac{1}{t} \log |y(-t, \omega) - Y(\theta(-t, \omega))| \leq -\lambda_{i_0-1}.$$

Each unstable subspace  $\mathcal{U}(\omega)$  of the linearized semiflow  $DU$  is tangent at  $Y(\omega)$  to  $\tilde{\mathcal{U}}(\omega)$ , viz.  $T_{Y(\omega)}\tilde{\mathcal{U}}(\omega) = \mathcal{U}(\omega)$ . In particular,  $\dim \tilde{\mathcal{U}}(\omega)$  is finite and non-random.

# Theorem 3-contd

(e) Let  $y(\cdot, x_i, \omega)$  be the history processes associated with  $x_i = y(0, x_i, \omega) \in \tilde{\mathcal{U}}(\omega)$ ,  $i = 1, 2$ . Then

$$\limsup_{t \rightarrow \infty} \frac{1}{t} \log \left[ \sup \left\{ \frac{|y(-t, x_1, \omega) - y(-t, x_2, \omega)|}{|x_1 - x_2|} : \right. \right. \\ \left. \left. x_1 \neq x_2, x_i \in \tilde{\mathcal{U}}(\omega), i = 1, 2 \right\} \right] \\ \leq -\lambda_{i_0-1}.$$

# Theorem 3-contd

---

*(f) (Cocycle-invariance of the unstable manifolds):*

*There exists  $\tau_2(\omega) \geq 0$  such that*

$$\tilde{\mathcal{U}}(\omega) \subseteq U(t, \cdot, \theta(-t, \omega))(\tilde{\mathcal{U}}(\theta(-t, \omega)))$$

*for all  $t \geq \tau_2(\omega)$ .*

# Theorem 3-contd

*(f) (Cocycle-invariance of the unstable manifolds):*

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$$\tilde{\mathcal{U}}(\omega) \subseteq U(t, \cdot, \theta(-t, \omega))(\tilde{\mathcal{U}}(\theta(-t, \omega)))$$

*for all  $t \geq \tau_2(\omega)$ . Also*

$$DU(t, \cdot, \theta(-t, \omega))(\mathcal{U}(\theta(-t, \omega))) = \mathcal{U}(\omega), \quad t \geq 0;$$

*and the restriction  $DU(t, \cdot, \theta(-t, \omega))|_{\mathcal{U}(\theta(-t, \omega))}$ ,  $t \geq 0$ , is a linear homeomorphism from  $\mathcal{U}(\theta(-t, \omega))$  onto  $\mathcal{U}(\omega)$ .*



# Theorem 3-contd

---

(g) The submanifolds  $\tilde{\mathcal{U}}(\omega)$  and  $\tilde{\mathcal{S}}(\omega)$  are transversal, viz.

$$H = T_{Y(\omega)}\tilde{\mathcal{U}}(\omega) \oplus T_{Y(\omega)}\tilde{\mathcal{S}}(\omega).$$

If  $F$  is  $C_b^\infty$ , then the local stable and unstable manifolds  $\tilde{\mathcal{S}}(\omega)$ ,  $\tilde{\mathcal{U}}(\omega)$  are  $C^\infty$ .

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# Theorem 3-contd

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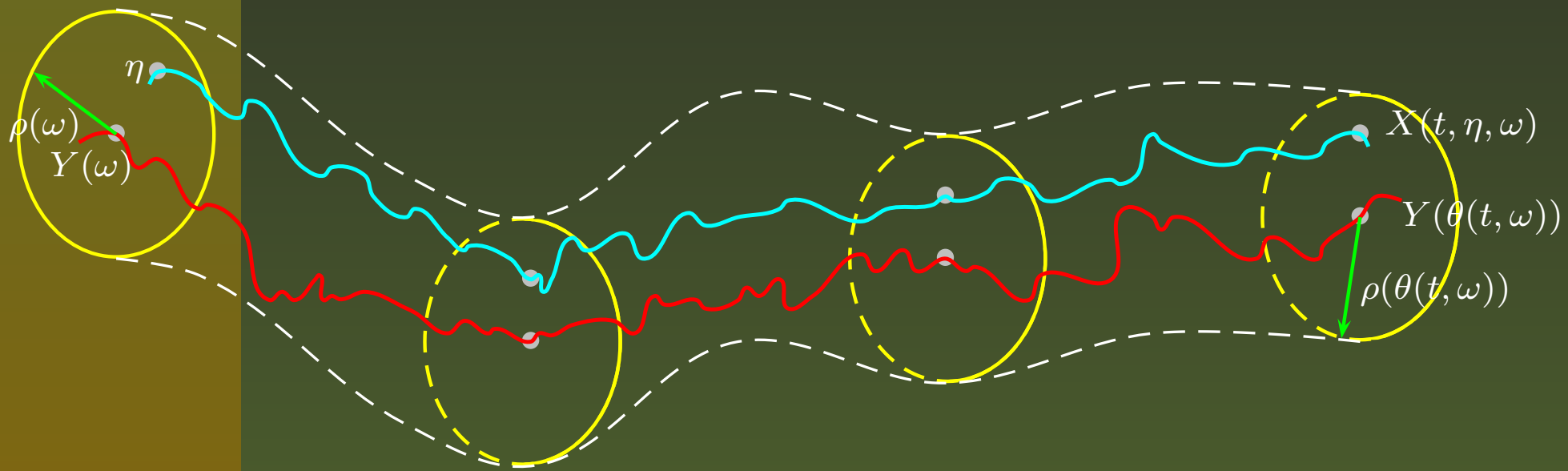
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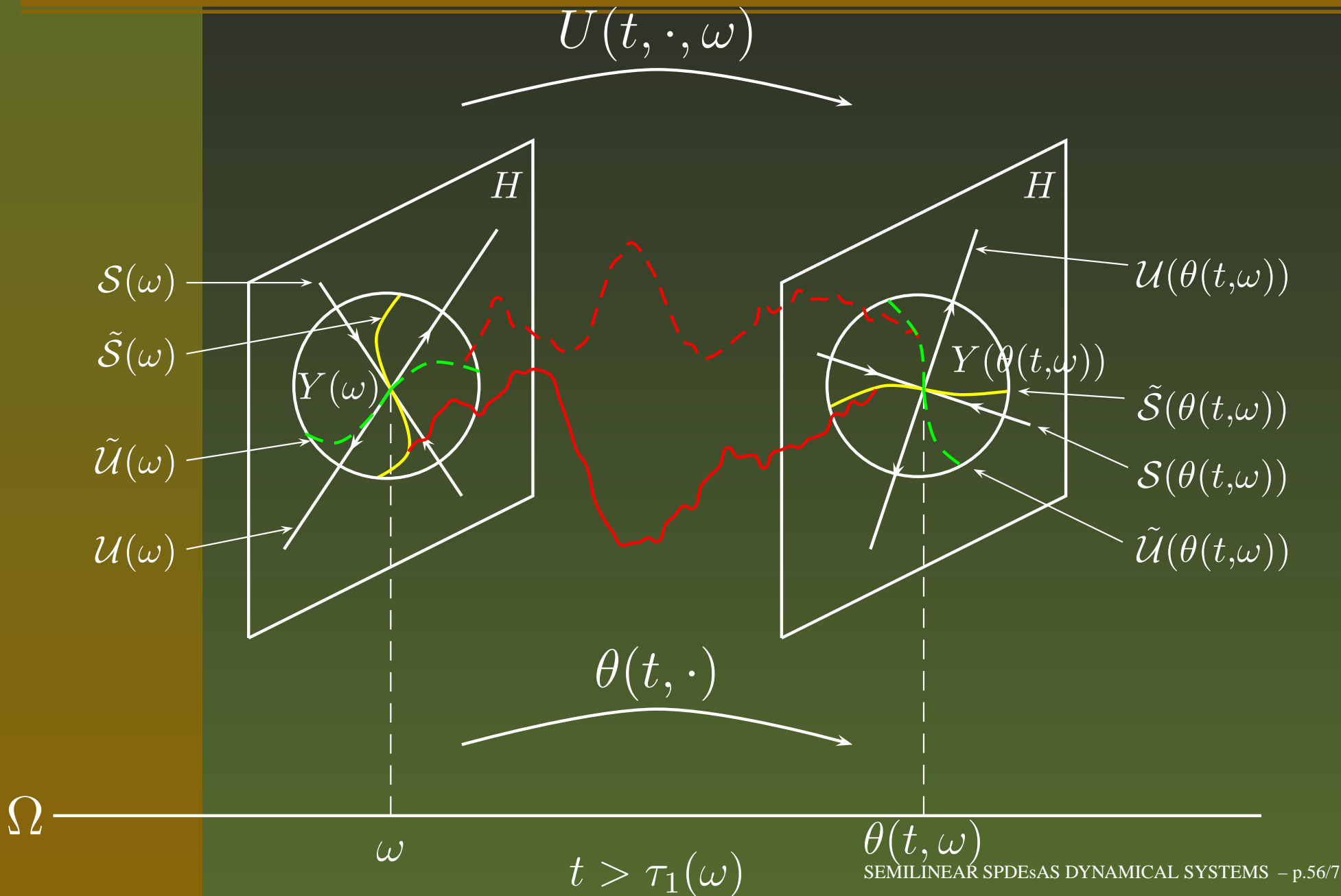
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*Ergodicity of  $Y$ :  $\tilde{\mathcal{U}}(\omega) = \{Y(\omega)\}$*

# A Stationary Tube



# Stable/Unstable Manifolds



# Examples Revisited

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Local stable manifold theorem applies to all examples:

- *Stochastic semilinear heat equation*

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Local stable manifold theorem applies to all examples:

- *Stochastic semilinear heat equation*
- *Stochastic semilinear parabolic pdes*
- *Stochastic reaction diffusion equations*
- *Stochastic Burgers equation*



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# SKETCH OF PROOF

# Proof of Theorem 3: Strategy

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- By definition, a *stationary* random point  $Y(\omega) \in H$  is invariant under the semiflow  $U$ ; viz  $U(t, Y) = Y(\theta(t, \cdot))$  for all times  $t$ .

# Proof of Theorem 3: Strategy

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- By definition, a *stationary* random point  $Y(\omega) \in H$  is invariant under the semiflow  $U$ ; viz  $U(t, Y) = Y(\theta(t, \cdot))$  for all times  $t$ .
- Linearize the semiflow  $U$  along the stationary point  $Y(\omega)$  in  $H$ . By stationarity of  $Y$  and the cocycle property of  $U$ , this gives a linear perfect cocycle  $(DU(t, Y), \theta(t, \cdot))$  in  $L(H)$ .

# Strategy-contd

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- Ergodicity of  $\theta$  allows for the notion of hyperbolicity of a stationary point of  $U$  via Oseledec-Ruelle theorem:



# Strategy-contd

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- **Ergodicity** of  $\theta$  allows for the notion of **hyperbolicity** of a stationary point of  $U$  via Oseledec-Ruelle theorem:

Use local compactness of the semiflow for positive  $t$ , and apply multiplicative ergodic theorem to get a discrete non-random Lyapunov spectrum  $\{\lambda_i : i \geq 1\}$  for the linearized cocycle.  $Y$  is *hyperbolic* if  $\lambda_i \neq 0$  for every  $i$ .

# Strategy-contd

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- Assume that  $\|Y\|^{\epsilon_0}$  is integrable (for small  $\epsilon_0$ ). Variational method of construction of the semiflow shows that the linearized cocycle satisfies hypotheses of **perfect versions** of ergodic theorem and Kingman's subadditive ergodic theorem. These refined versions give invariance of the Oseledec spaces under the **continuous-time** linearized cocycle. Thus the stable/unstable subspaces will serve as tangent spaces to the local stable/unstable manifolds of the non-linear semiflow  $U$ .

# Strategy-contd

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- Establish continuous-time integrability estimates on the spatial derivatives of the non-linear cocycle  $U$  in a neighborhood of the stationary point  $Y$ . Estimates follow from the variational construction of the stochastic semiflow.

# Strategy-contd

- Introduce the auxiliary perfect cocycle

$$Z(t, \cdot, \omega) := U(t, (\cdot) + Y(\omega), \omega) - Y(\theta(t, \omega)),$$
$$t \in \mathbf{R}^+, \omega \in \Omega.$$

Refine arguments in ([Ru.2], Theorems 5.1 and 6.1) to construct local stable/ unstable manifolds for the discrete cocycle  $(Z(n, \cdot, \omega), \theta(n, \omega))$  near 0 and hence (by translation) for  $U(n, \cdot, \omega)$  near  $Y(\omega)$  for all  $\omega$  sampled from a  $\theta(t, \cdot)$ -invariant sure event in  $\Omega$ .

# Strategy-contd

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- This is possible because of the **continuous-time** integrability estimates, the **perfect** ergodic theorem and the **perfect** subadditive ergodic theorem. By interpolating between discrete times and further refining the arguments in [Ru.2], show that the above manifolds also serve as local stable/unstable manifolds for the *continuous-time* semiflow  $U$  near  $Y$ .

# Strategy-contd

- Final key step:

Establish the asymptotic invariance of the local stable manifolds under the stochastic semiflow  $U$ . Use arguments underlying the proofs of Theorems 4.1 and 5.1 in [Ru.2] and some difficult estimates using the **continuous-time** integrability properties, and the **perfect** subadditive ergodic theorem.

Asymptotic invariance of the local unstable manifolds follows by employing the concept of a *stochastic history process* for  $U$  coupled with similar arguments to the above. Existence of history process compensates for the lack of invertibility of the semiflow. □

THANK YOU!

THE END!