# SFDE'S AS DYNAMICAL SYSTEMS I: THE LINEAR CASE

Warwick: November 10, 2000

#### Salah-Eldin A. Mohammed

Southern Illinois University

Carbondale, IL 62901–4408, USA

Web page: http://sfde.math.siu.edu

# 1. Regular Linear SFDE's-Ergodic Theory.

Linear sfde's on  $\mathbf{R}^d$  driven by m-dimensional Brownian motion  $W := (W_1, \dots, W_m)$ .

$$dx(t) = H(x(t - d_1), \dots, x(t - d_N), x(t), x_t)dt + \sum_{i=1}^{m} g_i x(t) dW_i(t), \quad t > 0$$

$$(x(0), x_0) = (v, \eta) \in M_2 := \mathbf{R}^d \times L^2([-r, 0], \mathbf{R}^d)$$
(I)

- (I) is defined on
- $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in \mathbf{R}}, P)$  = canonical complete filtered Wiener space.

 $\Omega := \text{space of all continuous paths } \omega : \mathbf{R} \to \mathbf{R}^m, \ \omega(0) = 0, \text{ in Euclidean space } \mathbf{R}^m, \text{ with compact open topology;}$ 

 $\mathcal{F} :=$ (completed) Borel  $\sigma$ -field of  $\Omega$ ;

 $\mathcal{F}_t := \text{(completed) sub-}\sigma\text{-field of }\mathcal{F} \text{ generated}$ by the evaluations  $\omega \to \omega(u), \ u \le t, \ t \in \mathbf{R}$ .

P :=Wiener measure on  $\Omega$ .

 $dW_i(t) = \text{It\^{o}}$  stochastic differentials.

Several finite delays  $0 < d_1 < d_2 < \cdots < d_N \le r$  in drift term; no delays in diffusion coefficient.

 $H: (\mathbf{R}^d)^{N+1} \times L^2([-r,0], \mathbf{R}^d) \to \mathbf{R}^d$  is a fixed continuous linear map,  $g_i, i = 1, 2, \dots, m$ , fixed (deterministic)  $d \times d$ -matrices.

#### 2. Plan

Use state space  $M_2 := \mathbf{R}^d \times L^2([-r, 0], \mathbf{R}^d)$ . For (I) consider the following themes:

I) Existence of a "perfect" cocycle on  $M_2$ -a modification of the trajectory field  $(x(t), x_t) \in M_2$ .

II) Existence of almost sure Lyapunov exponents

$$\lim_{t \to \infty} \frac{1}{t} \log \|(x(t), x_t)\|_{M_2}$$

Multiplicative ergodic theorem and hyperbolicity of cocycle.

III) "Random Saddle-Point Property" in hyperbolic case.

#### 3. Regularity

Say SFDE (I) is regular (wrt.  $M_2$ ) if trajectory  $\{(x(t), x_t) : (x(0), x_0) = (v, \eta) \in M_2\}$  admits a measurable modification  $X : \mathbf{R}^+ \times M_2 \times \Omega \to M_2$  such that  $X(\cdot, \cdot, \omega)$  is continuous for a.a.  $\omega \in \Omega$ .

#### **Theorem 1.**([Mo], 1990])

(I) is regular with respect to state space  $M_2 = \mathbf{R}^d \times \mathbf{L}^2([-r,0],\mathbf{R}^d)$ . There is a measurable version  $X:\mathbf{R}^+ \times \mathbf{R}^d$ 

 $M_2 \times \Omega \to M_2$  of the trajectory field  $\{(x(t), x_t) : t \in \mathbb{R}^+, (x(0), x_0) = (v, \eta) \in M_2\}$  of (I) with the following properties:

- (i) For each  $(v, \eta) \in M_2$  and  $t \in \mathbf{R}^+, X(t, (v, \eta), \cdot) = (x(t), x_t)$  a.s., is  $\mathcal{F}_t$ -measurable and belongs to  $L^2(\Omega, M_2; P)$ .
- (ii) There exists  $\Omega_0 \in \mathcal{F}$  of full measure such that, for all  $\omega \in \Omega_0$ , the map  $X(\cdot, \cdot, \omega) : \mathbf{R}^+ \times M_2 \to M_2$  is continuous.
- (iii) For each  $t \in \mathbf{R}^+$  and every  $\omega \in \Omega_0$ , the map  $X(t,\cdot,\omega): M_2 \to M_2$  is continuous linear; for each  $\omega \in \Omega_0$ , the map  $\mathbf{R}^+ \ni t \mapsto X(t,\cdot,\omega) \in L(M_2)$  is measurable and locally bounded in the uniform operator norm on  $L(M_2)$ . The map  $[r,\infty)\ni t\mapsto X(t,\cdot,\omega)\in L(M_2)$  is continuous for all  $\omega\in\Omega_0$ .

(iv) For each  $t \geq r$  and all  $\omega \in \Omega_0$ , the map

$$X(t,\cdot,\omega):M_2\to M_2$$

is compact.

Compactness of semi-flow for  $t \ge r$  will be used to define hyperbolicity for (I) and the associated exponential dichotomies.

Example: dx(t) = x(t-1) dW(t) is not regular (singular).

#### 4. Lyapunov Exponents. Hyperbolicity

Version X of the trajectory field of (I) (in Theorem 1) is a multiplicative  $L(M_2)$ -valued linear cocycle over the canonical Brownian shift  $\theta: \mathbf{R} \times \Omega \to \Omega$  on Wiener space:

$$\theta(t,\omega)(u) := \omega(t+u) - \omega(t), \quad u,t \in \mathbf{R}, \quad \omega \in \Omega.$$

I.e.

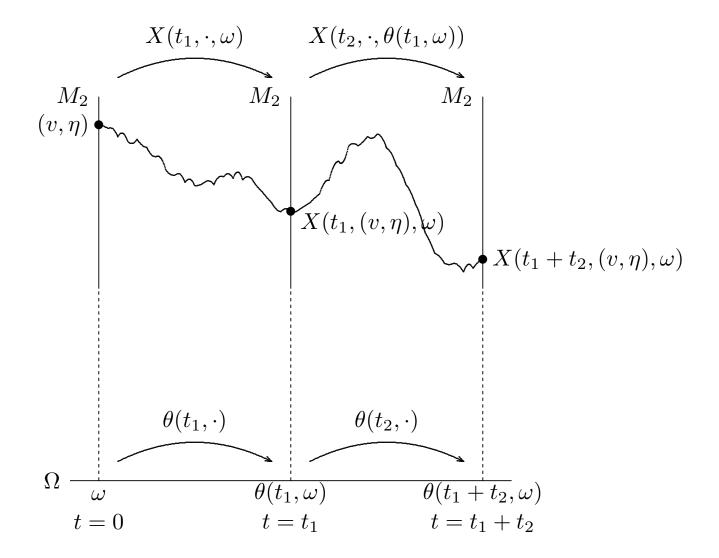
# **Theorem 2**([Mo], 1990)

There is an  $\mathcal{F}$ -measurable set  $\hat{\Omega}$  of full P-measure such that  $\theta(t,\cdot)(\hat{\Omega})\subseteq\hat{\Omega}$  for all  $t\geq 0$  and

$$X(t_2,\cdot,\theta(t_1,\omega))\circ X(t_1,\cdot,\omega)=X(t_1+t_2,\cdot,\omega)$$

for all  $\omega \in \hat{\Omega}$  and  $t_1, t_2 \geq 0$ .

## The Cocycle Property



Vertical solid lines represent random fibers: copies of  $M_2$ .  $(X, \theta)$  is a "vector-bundle morphism".

The a.s. Lyapunov exponents

$$\lim_{t \to \infty} \frac{1}{t} \log \|X(t, (v(\omega), \eta(\omega)), \omega)\|_{M_2},$$

(for a.a.  $\omega \in \Omega$ ,  $(v, \eta) \in L^2(\Omega, M_2)$ ) of the system (I) are characterized by the following "spectral theorem". Each  $\theta(t, \cdot)$  is ergodic and preserves Wiener measure P. The proof of Theorem 3 below uses compactness of  $X(t, \cdot, \omega) : M_2 \to M_2, t \geq r$ , together with an infinite-dimensional version of Oseledec's multiplicative ergodic theorem due to Ruelle (1982).

# **Theorem 3.** ([Mo], 1990)

Let  $X: \mathbf{R}^+ \times M_2 \times \Omega \to M_2$  be the flow of (I) given in Theorem 1. Then there exist

(a) an  $\mathcal{F}$ -measurable set  $\Omega^* \subseteq \Omega$  such that  $P(\Omega^*) = 1$  and  $\theta(t, \cdot)(\Omega^*) \subseteq \Omega^*$  for all  $t \ge 0$ ,

- (b) a fixed (non-random) sequence of real numbers  $\{\lambda_i\}_{i=1}^{\infty}$ , and
- (c) a random family  $\{E_i(\omega) : i \geq 1, \omega \in \Omega^*\}$  of (closed) finite-codimensional subspaces of  $M_2$ , with the following properties:
  - (i) If the **Lyapunov spectrum**  $\{\lambda_i\}_{i=1}^{\infty}$  is infinite, then  $\lambda_{i+1} < \lambda_i$  for all  $i \geq 1$  and  $\lim_{i \to \infty} \lambda_i = -\infty$ ; otherwise there is a fixed (non-random) integer  $N \geq 1$  such that  $\lambda_N = -\infty < \lambda_{N-1} < \cdots < \lambda_2 < \lambda_1$ ;
  - (ii) each map  $\omega \mapsto E_i(\omega)$ ,  $i \geq 1$ , is  $\mathcal{F}$ -measurable into the Grassmannian of  $M_2$ ;
  - (iii)  $E_{i+1}(\omega) \subset E_i(\omega) \subset \cdots \subset E_2(\omega) \subset E_1(\omega) =$  $M_2, i \geq 1, \omega \in \Omega^*;$
  - (iv) for each  $i \geq 1$ , codim  $E_i(\omega)$  is fixed independently of  $\omega \in \Omega^*$ ;

(v) for each  $\omega \in \Omega^*$  and  $(v, \eta) \in E_i(\omega) \setminus E_{i+1}(\omega)$ ,

$$\lim_{t \to \infty} \frac{1}{t} \log \|X(t, (v, \eta), \omega)\|_{M_2} = \lambda_i, \ i \ge 1;$$

(vi) Top Exponent:

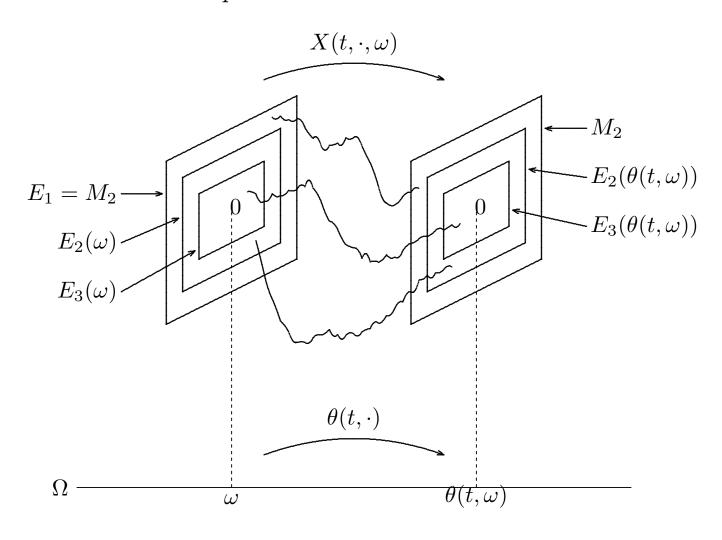
$$\lambda_1 = \lim_{t \to \infty} \frac{1}{t} \log \|X(t, \cdot, \omega)\|_{L(M_2)} \quad \text{for all } \omega \in \Omega^*;$$

(vii) Invariance:

$$X(t,\cdot,\omega)(E_i(\omega))\subseteq E_i(\theta(t,\omega))$$

for all  $\omega \in \Omega^*$ ,  $t \ge 0$ ,  $i \ge 1$ .

# Spectral Theorem



Proof of Theorem 3 is based on Ruelle's discrete version of Oseledec's multiplicative ergodic theorem in Hilbert space ([Ru], Ann. of Math. 1982, Theorem (1.1), p. 248 and Corollary (2.2), p. 253):

## **Theorem 4** ([Ru], 1982)

Let  $(\Omega, \mathcal{F}, P)$  be a probability space and  $\tau: \Omega \to \Omega$  a P-preserving transformation. Assume that H is a separable Hilbert space and  $T: \Omega \to L(H)$  a measurable map (w.r.t. the Borel field on the space of all bounded linear operators L(H)). Suppose that  $T(\omega)$  is compact for almost all  $\omega \in \Omega$ , and  $E\log^+ ||T(\cdot)|| < \infty$ . Define the family of linear operators  $\{T^n(\omega): \omega \in \Omega, n \geq 1\}$  by

$$T^{n}(\omega) := T(\tau^{n-1}(\omega)) \circ \cdots T(\tau(\omega)) \circ T(\omega)$$

for  $\omega \in \Omega$ ,  $n \ge 1$ .

Then there is a set  $\Omega_0 \in \mathcal{F}$  of full P-measure such that  $\tau(\Omega_0) \subseteq \Omega_0$ , and for each  $\omega \in \Omega_0$ , the limit

$$\lim_{n\to\infty} [T^n(\omega)^* \circ T^n(\omega)]^{1/(2n)} := \Lambda(\omega)$$

exists in the uniform operator norm and is a positive compact self-adjoint operator on H. Furthermore, each  $\Lambda(\omega)$ has a discrete spectrum

$$e^{\mu_1(\omega)} > e^{\mu_2(\omega)} > e^{\mu_3(\omega)} > e^{\mu_4(\omega)} > \cdots$$

where the  $\mu_i$ 's are distinct. If  $\{\mu_i\}_{i=1}^{\infty}$  is infinite, then  $\mu_i \downarrow -\infty$ ; otherwise they terminate at  $\mu_{N(\omega)} = -\infty$ . If  $\mu_i(\omega) > -\infty$ , then  $e^{\mu_i(\omega)}$  has finite multiplicity  $m_i(\omega)$  and finite-dimensional eigen-space  $F_i(\omega)$ , with  $m_i(\omega) := \dim F_i(\omega)$ . Define

$$E_1(\omega) := M_2, \quad E_i(\omega) := \left[ \bigoplus_{j=1}^{i-1} F_j(\omega) \right]^{\perp}, \quad E_{\infty}(\omega) := \ker \Lambda(\omega).$$

Then

$$E_{\infty}(\omega) \subset \cdots \subset E_{i+1}(\omega) \subset E_i(\omega) \cdots \subset E_2(\omega) \subset E_1(\omega) = H$$

and

$$\lim_{n \to \infty} \frac{1}{n} \log ||T^n(\omega)x||_H = \begin{cases} \mu_i(\omega), & \text{if } x \in E_i(\omega) \setminus E_{i+1}(\omega) \\ -\infty & \text{if } x \in \ker \Lambda(\omega). \end{cases}$$

#### Proof.

[Ru], Ann. of Math., 1982, pp. 248-254.

The following "perfect" version of Kingman's subadditive ergodic theorem is also used to construct the shift invariant set  $\Omega^*$  appearing in Theorem 3 above.

**Theorem 5**([M], 1990)("Perfect" Subadditive Ergodic Theorem)

Let  $f: \mathbf{R}^+ \times \Omega \to \mathbf{R} \cup \{-\infty\}$  be a measurable process on the complete probability space  $(\Omega, \mathcal{F}, P)$  such that

(i) 
$$E \sup_{0 \le u \le 1} f^+(u, \cdot) < \infty, E \sup_{0 \le u \le 1} f^+(1 - u, \theta(u, \cdot)) < \infty;$$

(ii)  $f(t_1+t_2,\omega) \leq f(t_1,\omega)+f(t_2,\theta(t_1,\omega))$  for all  $t_1,t_2 \geq 0$  and every  $\omega \in \Omega$ .

Then there exist a set  $\hat{\Omega} \in \mathcal{F}$  and a measurable  $\tilde{f} : \Omega \to \mathbf{R} \cup \{-\infty\}$  with the properties:

(a) 
$$P(\hat{\Omega}) = 1$$
,  $\theta(t, \cdot)(\hat{\Omega}) \subseteq \hat{\Omega}$  for all  $t \ge 0$ ;

(b) 
$$\tilde{f}(\omega) = \tilde{f}(\theta(t,\omega))$$
 for all  $\omega \in \hat{\Omega}$  and all  $t \geq 0$ ;

(c) 
$$\tilde{f}^+ \in \mathbf{L}^1(\Omega, \mathbf{R}; P);$$

(d) 
$$\lim_{t\to\infty} (1/t)f(t,\omega) = \tilde{f}(\omega)$$
 for every  $\omega \in \hat{\Omega}$ .

If  $\theta$  is ergodic, then there exist  $f^* \in \mathbf{R} \cup \{-\infty\}$  and  $\tilde{\tilde{\Omega}} \in \mathcal{F}$  such that

(a)' 
$$P(\tilde{\Omega}) = 1, \theta(t, \cdot)(\tilde{\Omega}) \subseteq \tilde{\Omega}, t \ge 0;$$

(b)' 
$$\tilde{f}(\omega) = f^* = \lim_{t \to \infty} (1/t) f(t, \omega)$$
 for every  $\omega \in \tilde{\tilde{\Omega}}$ .

#### Proof.

[Mo], Stochastics, 1990, Lemma 7, pp. 115–117.

Proof of Theorem 3 is an application of Theorem 4. Requires Theorem 5 and the following sequence of lemmas.

#### Lemma 1

For each integer  $k \ge 1$  and any  $0 < a < \infty$ ,

$$E \sup_{0 \le t \le a} \|\phi(t, \omega)^{-1}\|^{2k} < \infty;$$

$$E \sup_{0 \le t_1, t_2 \le a} \|\phi(t_2, \theta(t_1, \cdot))\|^{2k} < \infty.$$

#### Proof.

Follows by standard sode estimates, the cocycle property for  $\phi$  and Hölder's inequality. ([Mo], pp. 106-108).

The next lemma is a crucial estimate needed to apply Ruelle-Oseledec theorem (Theorem 4).

#### Lemma 2

$$E \sup_{0 \le t_1, t_2 \le r} \log^+ \|X(t_2, \cdot, \theta(t_1, \cdot))\|_{L(M_2)} < \infty.$$

#### Proof.

If  $y(t, (v, \eta), \omega)$  is the solution of the fde (8), then using Gronwall's inequality, taking

$$E \sup_{0 \le t_1, t_2 \le r} \log^+ \sup_{\|(v,\eta)\| \le 1}$$
 and applying Lemma 1, gives

$$E \sup_{0 \le t_1, t_2 \le r} \log^+ \sup_{\|(v,\eta)\| \le 1} \|(y(t_2, (v,\eta), \theta(t_1, \cdot)), y_{t_2}(\cdot, (v,\eta), \theta(t_1, \cdot)))\|_{M_2} < \infty.$$

Conclusion of lemma now follows by replacing  $\omega'$  with  $\theta(t_1, \omega)$  in the formula

$$X(t_2, (v, \eta), \omega')$$

$$= (\phi(t_2, \omega')(y(t_2, (v, \eta), \omega')), \phi_{t_2}(\cdot, \omega') \circ (id_J, y_{t_2}(\cdot, (v, \eta), \omega'))$$
and Lemma 1.

The existence of the Lyapunov exponents is obtained by interpolating the discrete limit

$$\frac{1}{r} \lim_{k \to \infty} \frac{1}{k} \log \|X(kr, (v(\omega), \eta(\omega)), \omega)\|_{M_2}, \qquad (12)$$

a.a.  $\omega \in \Omega$ ,  $(v, \eta) \in L^2(\Omega, M_2)$ , between delay periods of length r. This requires the next two lemmas.

#### Lemma 3

Let  $h: \Omega \to \mathbf{R}^+$  be  $\mathcal{F}$ -measurable and suppose  $E\sup_{0 \le u \le r} h(\theta(u, \cdot))$  is finite. Then

$$\Omega_1 := \left(\lim_{t \to \infty} \frac{1}{t} h(\theta(t, \cdot)) = 0\right)$$

is a sure event and  $\theta(t,\cdot)(\Omega_1) \subseteq \Omega_1$  for all  $t \geq 0$ .

#### Proof.

Use interpolation between delay periods and the discrete ergodic theorem applied to the  $L^1$  function

$$\hat{h} := \sup_{0 \le u \le r} h(\theta(u, \cdot).$$

([Mo], Stochastics, 1990, Lemma 5, pp. 111-113.)

#### Lemma 4

Suppose there is a sure event  $\Omega_2$  such that  $\theta(t,\cdot)(\Omega_2) \subseteq \Omega_2$  for all  $t \geq 0$ , and the limit (12) exists (or equal to  $-\infty$ ) for all  $\omega \in \Omega_2$  and all  $(v,\eta) \in M_2$ . Then there is a sure event  $\Omega_3$  such that  $\theta(t,\cdot)(\Omega_3) \subseteq \Omega_3$  and

$$\lim_{t \to \infty} \frac{1}{t} \log \|X(t, (v, \eta), \omega)\|_{M_2} = \frac{1}{r} \lim_{k \to \infty} \frac{1}{k} \log \|X(kr, (v, \eta), \omega)\|_{M_2},$$
(13)

for all  $\omega \in \Omega_3$  and all  $(v, \eta) \in M_2$ .

#### **Proof:**

Take  $\Omega_3 := \hat{\Omega} \cap \Omega_1 \cap \Omega_2$ . Use cocycle property for X, Lemma 2 and Lemma 3 to interpolate. ([Mo], Stochastics 1990, Lemma 6, pp. 113-114.)

#### Proof of Theorem 3. (Sketch)

Apply Ruelle-Oseledec Theorem (Theorem 4) with

 $T(\omega):=X(r,\omega)\in L(M_2), \text{ compact linear for } \omega\in\hat{\Omega};$ 

$$\tau: \Omega \to \Omega; \quad \tau := \theta(r, \cdot).$$

Then cocycle property for X implies

$$X(kr,\omega,\cdot) = T(\tau^{k-1}(\omega)) \circ T(\tau^{k-2}(\omega)) \circ \cdots \circ T(\tau(\omega)) \circ T(\omega)$$
$$:= T^{k}(\omega)$$

for all  $\omega \in \hat{\Omega}$ .

Lemma 2 implies

$$E \log^+ ||T(\cdot)||_{L(M_2)} < \infty.$$

Theorem 4 gives a random family of compact self-adjoint positive linear operators  $\{\Lambda(\omega) : \omega \in \Omega_4\}$  such that

$$\lim_{n\to\infty} [T^n(\omega)^* \circ T^n(\omega)]^{1/(2n)} := \Lambda(\omega)$$

exists in the uniform operator norm for  $\omega \in \Omega_4$ , a (continuous) shift-invariant set of full measure. Furthermore each  $\Lambda(\omega)$  has a discrete spectrum

$$e^{\mu_1(\omega)} > e^{\mu_2(\omega)} > e^{\mu_3(\omega)} > e^{\mu_4(\omega)} > \cdots$$

where the  $\mu'_i$ s are distinct, with no accumulation points except possibly  $-\infty$ . If  $\{\mu_i\}_{i=1}^{\infty}$  is infinite, then  $\mu_i \downarrow -\infty$ ; otherwise they terminate at  $\mu_{N(\omega)} = -\infty$ . If  $\mu_i(\omega) > -\infty$ , then  $e^{\mu_i(\omega)}$  has finite multiplicity  $m_i(\omega)$  and finite-dimensional eigenspace  $F_i(\omega)$ , with  $m_i(\omega) := \dim F_i(\omega)$ . Define

$$E_1(\omega) := M_2, \quad E_i(\omega) := \left[\bigoplus_{j=1}^{i-1} F_j(\omega)\right]^{\perp}, \quad E_{\infty}(\omega) := \ker \Lambda(\omega).$$

Then

$$E_{\infty}(\omega) \subset \cdots \subset E_{i+1}(\omega) \subset E_i(\omega) \cdots \subset E_2(\omega) \subset E_1(\omega) = M_2.$$

Note that  $\operatorname{codim} E_i(\omega) = \sum_{j=1}^{i-1} m_j(\omega) < \infty$ . Also

$$\lim_{k \to \infty} \frac{1}{k} \log \|X(kr, (v, \eta), \omega)\|_{M_2} = \begin{cases} \mu_i(\omega), & \text{if } (v, \eta) \in E_i(\omega) \setminus E_{i+1}(\omega) \\ -\infty & \text{if } (v, \eta) \in \text{ker } \Lambda(\omega). \end{cases}$$

The functions

$$\omega \mapsto \mu_i(\omega), \quad \omega \mapsto m_i(\omega), \quad \omega \mapsto N(\omega)$$

are invariant under the ergodic shift  $\theta(r,\cdot)$ . Hence they take the fixed values  $\mu_i$ ,  $m_i$ , N almost surely, respectively.

Lemma 4 gives a continuous-shift-invariant sure event  $\Omega^* \subseteq \Omega_4$  such that

$$\lim_{t \to \infty} \frac{1}{t} \log \|X(t, (v, \eta), \omega)\|_{M_2} = \frac{1}{r} \lim_{k \to \infty} \frac{1}{k} \log \|X(kr, (v, \eta), \omega)\|_{M_2}$$
$$= \frac{\mu_i}{r} =: \lambda_i,$$

for  $(v, \eta) \in E_i(\omega) \setminus E_{i+1}(\omega), \ \omega \in \Omega^*, i \ge 1$ .

 $\{\lambda_i := \frac{\mu_i}{r} : i \geq 1\}$  is the  $Lyapunov\ spectrum\$  of (I).

Since Lyapunov spectrum is discrete with no finite accumulation points, then  $\{\lambda_i : \lambda_i > \lambda\}$  is finite for all  $\lambda \in \mathbf{R}$ .

To prove invariance of the Oseledec space  $E_i(\omega)$  under the cocycle  $(X, \theta)$  use the random field

$$\lambda((v,\eta),\omega) := \lim_{t \to \infty} \frac{1}{t} \log \|X(t,(v,\eta),\omega)\|_{M_2}, \ (v,\eta) \in M_2, \ \omega \in \Omega^*$$

and the relations

$$E_i(\omega) := \{(v, \eta) \in M_2 : \lambda((v, \eta), \omega) \le \lambda_i\},\$$

$$\lambda(X(t,(v,\eta),\omega),\theta(t,\omega)) = \lambda((v,\eta),\omega), \quad \omega \in \Omega^*, \ t \ge 0$$

([Mo], Stochastics 1990, p. 122). 
$$\square$$

Lyapunov exponents  $\{\lambda_i\}_{i=1}^{\infty}$  of (I) are nonrandom because  $\theta$  is ergodic. Say (I) is hyperbolic if  $\lambda_i \neq 0$  for all  $i \geq 1$ . When (I) is hyperbolic the flow satisfies a stochastic saddle-point property (or exponential dichotomy) (cf. the deterministic case with  $E = C([-r, 0], \mathbf{R}^d)$ ,  $g_i \equiv 0$ ,  $i = 1, \ldots, m$ , in Hale [H], Theorem 4.1, p. 181).

# **Theorem 6** (Random Saddles)([Mo], 1990)

Suppose the sfde (I) is hyperbolic. Then there exist

- (a) a set  $\tilde{\Omega}^* \in \mathcal{F}$  such that  $P(\tilde{\Omega}^*) = 1$ , and  $\theta(t, \cdot)(\tilde{\Omega}^*) = \tilde{\Omega}^*$  for all  $t \in \mathbf{R}$ , and
- (b) a measurable splitting

$$M_2 = \mathcal{U}(\omega) \oplus \mathcal{S}(\omega), \qquad \omega \in \tilde{\Omega}^*,$$

with the following properties:

- (i)  $\mathcal{U}(\omega)$ ,  $\mathcal{S}(\omega)$ ,  $\omega \in \tilde{\Omega}^*$ , are closed linear subspaces of  $M_2$ , dim  $\mathcal{U}(\omega)$  is finite and fixed independently of  $\omega \in \tilde{\Omega}^*$ .
- (ii) The maps  $\omega \mapsto \mathcal{U}(\omega)$ ,  $\omega \mapsto \mathcal{S}(\omega)$  are  $\mathcal{F}$ -measurable into the Grassmannian of  $M_2$ .
- (iii) For each  $\omega \in \tilde{\Omega}^*$  and  $(v, \eta) \in \mathcal{S}(\omega)$  there exists  $\tau_1 = \tau_1(v, \eta, \omega) > 0$  and a positive  $\delta_1$ , independent of  $(v, \eta, \omega)$  such that

$$||X(t,(v,\eta),\omega)||_{M_2} \le ||(v,\eta)||_{M_2} e^{-\delta_1 t}, \quad t \ge \tau_1.$$

(iv) For each  $\omega \in \tilde{\Omega}^*$  and  $(v, \eta) \in \mathcal{U}(\omega)$  there exists  $\tau_2 = \tau_2(v, \eta, \omega) > 0$  and a positive  $\delta_2$ , independent of  $(v, \eta, \omega)$  such that

$$||X(t,(v,\eta),\omega)||_{M_2} \ge ||(v,\eta)||_{M_2} e^{\delta_2 t}, \quad t \ge \tau_2.$$

(v) For each  $t \geq 0$  and  $\omega \in \tilde{\Omega}^*$ ,

$$X(t, \omega, \cdot)(\mathcal{U}(\omega)) = \mathcal{U}(\theta(t, \omega)),$$
$$X(t, \omega, \cdot)(\mathcal{S}(\omega)) \subseteq \mathcal{S}(\theta(t, \omega)).$$

In particular, the restriction

$$X(t,\omega,\cdot) \mid \mathcal{U}(\omega) : \mathcal{U}(\omega) \to \mathcal{U}(\theta(t,\omega))$$

is a linear homeomorphism onto.

#### Proof.

[Mo], Stochastics, 1990, Corollary 2, pp. 127-130.  $\Box$ 

# The Saddle-Point Property

